

3/28/06

From 3/23:

$$E_2 = \sum g_i P_i + dt H(\vec{q}, \vec{P}, t) \Rightarrow$$

$$\vec{q}(t_0) \rightarrow \vec{q} = \vec{q}(t + dt)$$

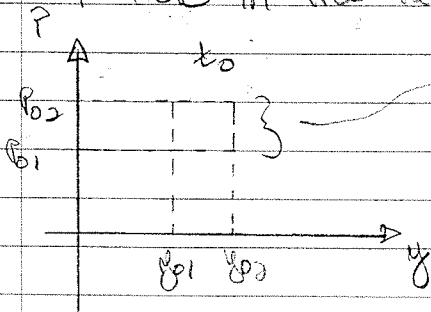
$$Q_i = \frac{\partial E_2}{\partial P_i} = q_i + \dot{q}_i dt$$

$$P_i = \frac{\partial E_2}{\partial q_i} = P_i - \dot{p}_i dt$$

$$P_i = p_i + \dot{p}_i dt$$

$$\vec{q} \rightarrow \vec{Q} \Rightarrow \bar{M}_{ij} = \frac{\partial \dot{q}_i}{\partial \dot{q}_j} \text{ so } \bar{M} \bar{J} \bar{M}^T = \bar{J} \\ \bar{M}^T \bar{J} \bar{M} = \bar{J}$$

Example: Louisville's Theorem
Particle in free fall



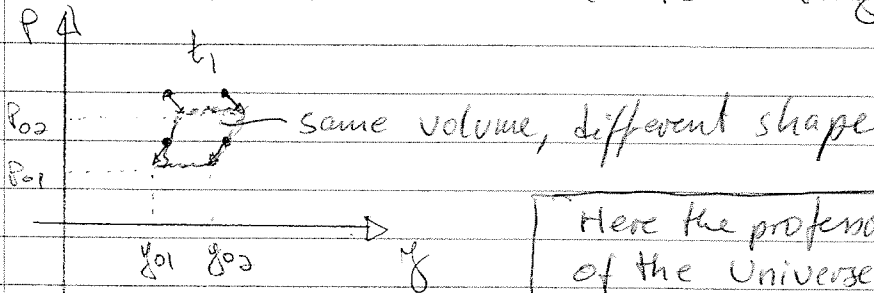
Rectangle bounds systems with different initial conditions but same hamiltonian =>

$$H = \frac{p^2}{2m} + mgy$$

where $y(t) = y_0 + \frac{p_0}{m} t - \frac{1}{2} g t^2$

and $p(t) = p_0 - mgt$

Consider the four corners of the rectangle at a later time



Here the professor explained the secrets of the Universe, but if you don't come to class, you'll never know them. Hint: The answer is "49"

Poisson Brackets

Consider two functions $u(\vec{p}, \vec{q}, t)$, $v(\vec{p}, \vec{q}, t)$.
The Poisson Bracket is defined as

$$[u, v]_{\vec{q}, \vec{p}} = \sum_i \left(\frac{\partial u}{\partial q_i} \frac{\partial v}{\partial p_i} - \frac{\partial u}{\partial p_i} \frac{\partial v}{\partial q_i} \right)$$

Some examples:

$$[q_j, q_k]_{\vec{q}, \vec{p}} = 0$$

$$[p_j, p_k]_{\vec{q}, \vec{p}} = 0$$

$$[q_j, p_k]_{\vec{q}, \vec{p}} = \delta_{jk}$$

$$[u, v] = -[v, u]$$

Notice $\sum_i \left(\frac{\partial u}{\partial q_i} \frac{\partial v}{\partial p_i} - \frac{\partial u}{\partial p_i} \frac{\partial v}{\partial q_i} \right) = \left(\frac{\partial u}{\partial \vec{q}} \right)^T \bar{J} \left(\frac{\partial v}{\partial \vec{q}} \right)$

so $[q_j, q_k]_{\vec{q}} = \bar{J}_{jk}$

Suppose \vec{q}, \vec{p} are canonically transformed. Then

$$[q_j, q_k]_{\vec{q}} = \left(\frac{\partial q_j}{\partial \vec{q}} \right)^T \bar{J} \left(\frac{\partial q_k}{\partial \vec{q}} \right)$$

To find a component,

$$[q_j, q_j]_{\vec{q}} = \left(\frac{\partial q_j}{\partial \vec{q}} \right)^T \bar{J} \left(\frac{\partial q_j}{\partial \vec{q}} \right) = \bar{M}^T \bar{J} \bar{M} = \bar{J}$$

which implies $[q_j, q_j]_{\vec{q}} = [q_j, q_j]_{\vec{q}}$. Vice versa,

$$[q_j, q_j]_{\vec{q}} = [q_j, q_j]_{\vec{q}}$$

\Rightarrow Poisson brackets are independent of canonical variables

[invariant under canonical transformations]

Example 1

Let $u = u(\vec{p}, \vec{q}, t)$. Then

$$\begin{aligned} [u, H] &= \sum_i \left(\frac{\partial u}{\partial q_i} \frac{\partial H}{\partial p_i} - \frac{\partial u}{\partial p_i} \frac{\partial H}{\partial q_i} \right) \\ &= \sum_i \left(\frac{\partial u}{\partial q_i} \dot{q}_i + \frac{\partial u}{\partial p_i} \dot{p}_i \right) \\ &= \frac{du}{dt} - \frac{\partial u}{\partial t} \end{aligned}$$

So

$$\frac{du}{dt} = [u, H] + \frac{\partial u}{\partial t}$$

If u is conserved, then $[u, H] \neq 0 \Rightarrow [u, H] + \frac{\partial u}{\partial t} = 0$

$$[H, u] = \partial u / \partial t$$

Observe

$$\left. \begin{aligned} [\vec{p}, H] &= \dot{\vec{p}} \\ [\vec{q}, H] &= \dot{\vec{q}} \end{aligned} \right\} = \left(\frac{\partial \vec{q}}{\partial \vec{q}} \right) \left(\vec{J} \right) \left(\frac{\partial H}{\partial \vec{q}} \right)$$

Example 2

$$[u, p_\delta] = \frac{\partial u}{\partial q_\delta} \Rightarrow$$

$$[u, p_\delta] \delta q_\delta = \frac{\partial u}{\partial q_\delta} \delta q_\delta = \partial u$$

$$dt [u, H] = \left(\frac{du}{dt} - \frac{\partial u}{\partial t} \right) \delta t$$

If $\frac{\partial u}{\partial t} = 0$, then

$$dt [u, H] = du$$

- OR -

$$\vec{\eta} + \delta \vec{\eta} ; \delta \vec{\eta} = dt [\vec{\eta}, H] = dt \vec{J} \left(\frac{\partial H}{\partial \vec{q}} \right)$$