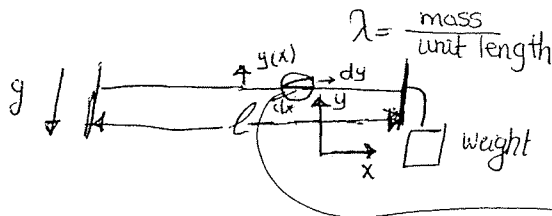


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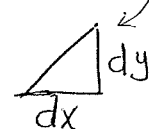
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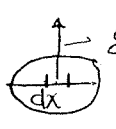
Lagrangian Dynamics for ∞ degrees of freedom:

Ex 1-



This string is carrying a mass, so it has a tension (T)

$$\text{actual length} = \int_0^l \sqrt{dx^2 + dy^2} = \int_0^l \sqrt{1 + y'^2(x)} dx$$


$$\text{To get the K.E } T = \int_0^l \frac{\dot{y}^2}{2} \lambda dx =$$


$$\text{The pot. Energy} = (\text{Actual length} - l) T$$

$$\text{Actual length} = \int_0^l \left(1 + \frac{y'^2(x)}{2}\right) dx \quad \left(1^{\text{st}} \text{ order approximation Taylor series expansion of } \sqrt{1 + y'^2}\right)$$

$$E = l + \int_0^l \frac{y'^2(x)}{2} dx$$

\Rightarrow So the Lagrangian will be

$$L = \int_0^l \left(\frac{\lambda}{2} \dot{y}^2 - \frac{T}{2} y'^2 \right) dx$$

This Lagrangian has problem
 - it integrates over whole no. of degrees of freedom
 - it contains y' and we don't know how to solve y'

at the end of string from both sides ($y=0$)
 we made the following assumption

$$y(x) = \sum_{n=1}^{\infty} a_n \sin k_n x \quad \text{under condition } k_n l = n\pi \Rightarrow k_n = \frac{n\pi}{l}$$

[2]

$$\dot{y}(x) = \sum_{n=1}^{\infty} \dot{a}_n \sin k_n x \quad , \quad [\text{using Fourier Theorem}]$$

$$\text{for } y' = \sum_{n=1}^{\infty} a_n k_n \cos k_n x$$

$$\text{So } L = \frac{\lambda}{2} \int_0^l \sum_{n,m} \dot{a}_n \dot{a}_m \sin \frac{k_n x}{\frac{n\pi}{l}} \sin \frac{k_m x}{\frac{m\pi}{l}} dx$$

$$- \frac{\tau}{2} \int_0^l \sum_{n,m} a_n k_n a_m k_m \cos k_n x \cos k_m x dx$$

$$\text{Take } \theta = \frac{\pi x}{l}$$

$$L = \frac{\lambda l}{2\pi} \int_0^{\pi} \sum_{n,m} \dot{a}_n \dot{a}_m \sin n\theta \sin m\theta d\theta - \frac{\tau}{2} \frac{l}{\pi} \int_0^{\pi} \sum_{n,m} a_n a_m k_n k_m \cos n\theta \cos m\theta d\theta$$

$\Rightarrow = \frac{\pi}{2} \quad \text{if } n=m$
 $\quad \quad \quad 0 \quad \text{if } n \neq m$

$$= -\frac{\tau}{2} \frac{l}{2} \sum_n \dot{a}_n^2 k_n^2 + \frac{\lambda l}{4} \sum_n \dot{a}_n^2$$

So that the Lagrangian

$$\mathcal{L} = \frac{\lambda l}{4} \sum_n \dot{a}_n^2 - \frac{l\tau}{4} \sum_n a_n^2 k_n^2$$

(now our new coordinates are a_n and \dot{a}_n)

$$\text{Using E-L } \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{a}_n} - \frac{\partial \mathcal{L}}{\partial a_n} = 0$$

$$\frac{d}{dt} 2 \frac{\lambda l}{4} \dot{a}_n + \frac{l\tau}{4} 2 a_n k_n^2 = 0$$

$$\Rightarrow \ddot{a}_n + \frac{\tau}{\lambda} a_n k_n^2 = 0$$

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So the last equ. is a simple harmonic oscillation with amplitude
frequency $\frac{\tau k_n^2}{\lambda} = \omega^2$

$$y(x,t) = \sum_n A_n \cos \omega_n t \sin k_n x$$

(1)

where $k_n = \frac{n\pi}{l}$, $\omega_n = k_n \sqrt{\frac{\tau}{\lambda}} = \frac{n\pi}{l} \sqrt{\frac{\tau}{\lambda}}$

This is an equ. of Standing wave which depends on time and position

$$T = \frac{2\pi}{\omega} = \frac{2l}{n} \sqrt{\frac{\lambda}{\tau}}$$

$\sqrt{\frac{\tau}{\lambda}}$ → This describes the velocity

- if we want to take the gravitational pot. on the string we should add

$\int_0^l y \lambda g dx$ to the pot. energy

from least action principle:-

$$\delta \int_{t_1}^{t_2} L dt = 0$$

lets we have a field $\eta(x,t)$

Example Take $L = \frac{\lambda}{2} \dot{y}^2 - \frac{\tau}{2} y'^2 - \lambda g y$ with "field" $y(x,t)$

$$\text{So } \mathcal{L} = \int_{x_1}^{x_2} \mathcal{L}(\eta, \dot{\eta}, \eta', x, t) dx$$

$$\boxed{4} \quad S = \int_{t_1}^{t_2} dt \int_{x_1}^{x_2} \mathcal{L}(\eta, \dot{\eta}, \eta', x, t) dx$$

$$\eta_0(x, t) \xrightarrow{\delta} \eta_0 + \delta\eta \cdot \alpha, \quad \delta\eta(x_1) = \delta\eta(x_2) = 0$$

$$\text{in addition } \delta\eta(x, t_1) = \delta\eta(x, t_2) = 0$$

but inside between x_1 and x_2 and (t_1 and t_2)
everything can vary

$$0 = \frac{\partial S}{\partial \alpha} = \int_{t_1}^{t_2} dt \int_{x_1}^{x_2} dx \left(\frac{\partial \mathcal{L}}{\partial \eta} \delta\eta + \frac{\partial \mathcal{L}}{\partial \dot{\eta}} \delta\dot{\eta} + \frac{\partial \mathcal{L}}{\partial \eta'} \delta\eta' \right)$$

$$\left(\frac{\partial \mathcal{L}}{\partial \eta} - \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{\eta}} - \frac{d}{dx} \frac{\partial \mathcal{L}}{\partial \eta'} \right) \delta\eta$$

$$\int dt \frac{\partial \mathcal{L}}{\partial \dot{\eta}} \delta\dot{\eta} = \frac{\partial \mathcal{L}}{\partial \dot{\eta}} \delta\eta \Big|_{t_1}^{t_2} - \int \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{\eta}} \delta\eta$$

$$\int dx \frac{\partial \mathcal{L}}{\partial \eta'} \delta\eta' = \frac{\partial \mathcal{L}}{\partial \eta'} \delta\eta \Big|_{x_1}^{x_2} - \int \frac{d}{dx} \frac{\partial \mathcal{L}}{\partial \eta'} \delta\eta$$

$$\text{ELE. } \left\{ \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{\eta}} + \frac{d}{dx} \frac{\partial \mathcal{L}}{\partial \eta'} - \frac{\partial \mathcal{L}}{\partial \eta} = 0 \right\}$$

if we take the gravitational pot. the Lagrangian density

$$\left\{ \mathcal{L} = \frac{\lambda}{2} \dot{y}^2 - \frac{T}{2} y'^2 - \lambda g y \right\}$$

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so ELE $\frac{d}{dt} \lambda \dot{y} - \frac{d}{dx} \tau y' + \lambda g = 0$

$$\Rightarrow \lambda \ddot{y} - \tau y'' + \lambda g = 0$$

Stationary solution when $\ddot{y} = 0$

$$y'' = \frac{\lambda g}{\tau}$$

$$y = y_0 + y'_0 x + \frac{1}{2} \frac{\lambda g}{\tau} x^2$$

$$y(0) = 0 \Rightarrow y_0 = 0$$

$$y(l) = 0 \quad y'_0 l + \frac{\lambda g}{2\tau} l^2 = 0$$

$$y'_0 = -\frac{\lambda g l}{2\tau}$$

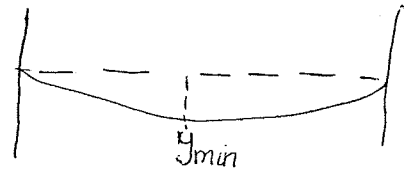
To get y_{\min} (That's occurred at $x = l/2$)

$$y_{\min} = -\frac{\lambda g l^2}{4\tau} + \frac{1}{8} \frac{\lambda g l^2}{\tau}$$

$$y_{\min} = -\frac{\lambda g l^2}{8\tau}$$

Dynamics is

$$\lambda \ddot{y} - \tau y'' = 0$$



The solution will be $y(x,t) = f(kx - \omega t)$

$$\ddot{y} = \omega^2 y \quad y'' = k^2 y$$

arbitrary function f

$$c = \omega/k$$

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$$\text{so } \lambda \omega^2 - \tau k^2 = 0$$

$$\Rightarrow \omega = k \sqrt{\frac{\tau}{\lambda}} \quad c = \sqrt{\frac{\tau}{\lambda}}$$

The same result as 4

3D

* To describe a field

$$\eta = \eta(\vec{r}, t)$$

1) describe the Lagrangian density

$$\mathcal{L}(\eta, \vec{\nabla} \eta, \dot{\eta}, \vec{r}, t)$$

$$2) \text{ "Lagrangian" } = \iiint d^3 \vec{r} \mathcal{L}$$

$$3) \int_{t_1}^{t_2} \mathcal{L} dt \text{ is stationary} = \iiint dt d^3 \vec{r} \mathcal{L}$$

$$4) \text{ E-L-E } \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{\eta}} + \vec{\nabla} \frac{\partial \mathcal{L}}{\partial \vec{\nabla} \eta} - \frac{\partial \mathcal{L}}{\partial \eta} = 0$$

$$\frac{d}{dx} \frac{\partial \mathcal{L}}{\partial \dot{\eta}_{\partial x}} + \frac{d}{dy} \frac{\partial \mathcal{L}}{\partial \dot{\eta}_{\partial y}} + \frac{d}{dz} \frac{\partial \mathcal{L}}{\partial \dot{\eta}_{\partial z}}$$

Straightforward application to relativity