

Example 5

$$H = \frac{p^2}{2m} + \frac{1}{2} m \omega^2 q^2$$

$$q = A \sin \omega t \quad (1)$$

$$p = m \omega A \cos \omega t \quad (2)$$

$$Q = \omega t \quad P = c A^n$$

We're looking for $F_1(q, Q, t)$, such that

$$\frac{\partial F_1}{\partial q} = p = m \omega A \cos \omega t = m \omega A \cos Q$$

from (1) $A = \frac{q}{\sin Q}$

$$\Rightarrow \frac{\partial F_1}{\partial q} = m \omega q \cot Q = p$$

$$-\frac{\partial F_1}{\partial Q} = P = c \left(\frac{q}{\sin Q} \right)^n$$

$$\frac{\partial^2 F_1}{\partial Q \partial q} = \frac{\partial^2 F_1}{\partial q \partial Q} \Rightarrow -m \omega q \frac{1}{\sin^2 Q} = -c \frac{n q^{n-1}}{\sin^n Q}$$

$$\Rightarrow n=2 \quad \text{and} \quad -m \omega = -2c, \quad c = \frac{m \omega}{2}$$

$$\Rightarrow \left\{ \begin{array}{l} \frac{\partial F_1}{\partial q} = m \omega q \cot Q = p \\ \frac{\partial F_1}{\partial Q} = -\frac{m \omega}{2} q^2 \frac{1}{\sin^2 Q} \end{array} \right.$$

$$\Rightarrow F_1 = \underbrace{\frac{m \omega q^2}{2} \cot Q}$$

⇒ Although canonical transformations Q and P depended on t , F_2 doesn't depend.

$$K = H + \frac{\partial F_2}{\partial t} = H \quad \text{is total energy}$$

$$P = cA^2, \quad A = \sqrt{\frac{P}{c}} \quad \Rightarrow \quad q = \sqrt{\frac{2P}{m\omega}} \sin Q$$

$$P = \sqrt{2Pm\omega} \cos Q$$

$$\begin{aligned} K &= \frac{2Pm\omega}{2m} \cos^2 Q + \frac{1}{2} m\omega^2 \frac{2P}{m\omega} \sin^2 Q = \\ &= \omega P \cos^2 Q + \omega P \sin^2 Q = \omega P \end{aligned}$$

$$\Rightarrow E = \underset{\substack{\downarrow \\ \text{value of } K}}{\frac{1}{2} k} A^2 = \underset{\substack{\downarrow \\ m\omega^2}}{\frac{1}{2} k} \frac{P}{c}$$

Because K_0 doesn't depend on $Q \Rightarrow P = \text{const}$

We could use these results also to find $q(t)$, and $p(t)$

$$\dot{Q} = \frac{\partial K}{\partial P} = \omega$$

$$Q = \omega t + \varphi_0$$

$$\Rightarrow q(t) = \sqrt{\frac{2P}{m\omega}} \sin(\omega t + \varphi_0) = \sqrt{\frac{2E}{m\omega^2}} \sin(\omega t + \varphi_0)$$

We have $F = F_1(q, Q, t)$

$$\frac{\partial F_1}{\partial q} = p \quad \frac{\partial F_1}{\partial Q} = -P$$

Sometimes this doesn't work. So we use

$$F = F_2(q, P, t) - \sum Q_i P_i$$

$$\sum p_i \dot{q}_i - H = \sum P_i \dot{Q}_i - K + \frac{dF}{dt}$$

$$\frac{dF}{dt} = -\sum \dot{Q}_i P_i - \sum Q_i \dot{P}_i + \sum \left(\frac{\partial F_2}{\partial q_i} \dot{q}_i + \frac{\partial F_2}{\partial P_i} \dot{P}_i \right) + \frac{\partial F_2}{\partial t}$$

We require $p_i = \frac{\partial F_2}{\partial q_i}$ and $Q_i = \frac{\partial F_2}{\partial P_i}$

$$\Rightarrow H = K - \frac{\partial F_2}{\partial t}$$

Example 6

$$F_2 = \sum_i q_i P_i \Rightarrow p_i = P_i, \quad Q_i = q_i$$

and there is nothing new done

$$\text{let's chose } F_2 = \left(\sum_i f_i(\vec{q}) P_i \right) + g(\vec{q})$$

(general form)

$$Q_i = f_i(\vec{q}) \quad (\text{transf.-n in configuration space})$$

$$P_j = \left(\sum_i \frac{\partial f_i}{\partial q_j} P_i \right) + \frac{\partial g}{\partial q_j} \Rightarrow \vec{P} = \left(\frac{\partial f}{\partial \vec{q}} \right) (\vec{P}) + \left(\frac{\partial g}{\partial \vec{q}} \right)$$

Now we can redo all we have done, using matrix form.

$$(1) \dot{q}_i = \frac{\partial H}{\partial p_i}, \quad (2) \dot{p}_i = -\frac{\partial H}{\partial q_i}$$

Introduce; $\vec{\eta} = \begin{pmatrix} q_1 \\ \vdots \\ q_k \\ p_1 \\ \vdots \\ p_k \end{pmatrix}$; $\frac{\partial H}{\partial \vec{\eta}} = \begin{pmatrix} \frac{\partial H}{\partial q_1} \\ \vdots \\ \frac{\partial H}{\partial q_k} \\ \frac{\partial H}{\partial p_1} \\ \vdots \\ \frac{\partial H}{\partial p_k} \end{pmatrix}$

$$\Rightarrow \dot{\vec{\eta}} = \underbrace{\begin{pmatrix} 0 & \mathbb{1}_{k \times k} \\ -\mathbb{1} & 0 \end{pmatrix}}_{\mathcal{J}} \left(\frac{\partial H}{\partial \vec{\eta}} \right)$$

symplectic matrix

(Symplectic formulation)

Introduce; $\vec{\xi} = \begin{pmatrix} Q_1 \\ \vdots \\ Q_k \\ P_1 \\ \vdots \\ P_k \end{pmatrix}$

$$\dot{\vec{\xi}} = (\mathcal{J}) \left(\frac{\partial K}{\partial \vec{\xi}} \right)$$

HEM for new hamiltonian $K(\vec{\xi})$

Let's assume this transformation is not time dependent.

$$\dot{\vec{\xi}} = \underbrace{\left(\frac{\partial \xi_i}{\partial \eta_j} \right)}_{\text{Jacobian matrix } (M_{ij})} \dot{\vec{\eta}}$$

$$\Rightarrow \begin{pmatrix} \dot{\vec{q}} \end{pmatrix} = (M_{ij})(\vec{q}) \left(\frac{\partial H}{\partial \vec{p}} \right)$$

As K is same as H (except some variables), we can write:

$$\left(\frac{\partial H}{\partial \vec{q}} \right) = \left(\frac{\partial \vec{F}}{\partial \vec{q}} \right) \left(\frac{\partial K}{\partial \vec{F}} \right)$$

$$\frac{\partial H}{\partial q_i} = \sum_j \frac{\partial \mathcal{F}_j}{\partial q_i} \frac{\partial K}{\partial \mathcal{F}_j}$$

$$\Rightarrow \begin{pmatrix} \dot{\vec{q}} \end{pmatrix} = (M_{ij})(\vec{q}) (M_{ji}) \left(\frac{\partial K}{\partial \vec{F}} \right) =$$

$$= (M)(\vec{q})(M)^T \left(\frac{\partial K}{\partial \vec{F}} \right)$$

So we can conclude:

$$(*) \quad \boxed{(\vec{q}) = (M)(\vec{q})(M)^T} \quad \left(\begin{array}{l} \text{Symplectic} \\ \text{condition} \end{array} \right)$$

So now we can use this and check if transformation is canonical.

If we take det of $(*) \Rightarrow \det(M) = 1$

$$\Rightarrow \int_{(2n)} \dots \underbrace{\left| \frac{\partial \vec{F}}{\partial \vec{q}} \right|}_{|M|=1} d^{2n} \vec{q} = \int_{(2n)} \dots d^{2n} \vec{F} \Rightarrow \text{volume under canonical tr.-n doesn't change}$$

Assume we have a transf.-n of following kind;

$$\vec{\eta}(t_0) \rightarrow \vec{\eta}(t) = \vec{\eta}(t_0) + dt \dot{\vec{\eta}} = \vec{\zeta}$$

↓
short time
after t_0
(infinitesimal
transformation - ICT)
canonical

Now let's try to find gen. f.-n for this transf.-n.

We need to use identity tr.-n + smth. \Rightarrow

$$F_2 = \sum q_i P_i + dt G(\vec{q}, \vec{P}, t) \quad P_i = \frac{\partial F_2}{\partial q_i} \quad Q_i = \frac{\partial F_2}{\partial p_i}$$

$$p_i = P_i + dt \frac{\partial G}{\partial q_i}, \quad Q_i = q_i + dt \frac{\partial G}{\partial P_i}$$

$$P_i = p_i + dt \dot{p}_i$$

$$\dot{p}_i = - \left. \frac{\partial G}{\partial q_i} \right|_{\vec{q}, \vec{P}=\vec{p}} \quad \dot{q}_i = \left. \frac{\partial G}{\partial P_i} \right|_{\vec{q}, \vec{P}=\vec{p}}$$

$\left(\dot{\vec{\eta}} \right) = \left(\mathcal{Y} \right) \left(\frac{\partial G}{\partial \vec{\eta}} \right) \times dt \Rightarrow$
}

 small change
 from $\frac{\partial G}{\partial \dots}(\vec{q}, \vec{P})$
 2nd order in dt
 \rightarrow can neglect

$$\Rightarrow \delta(\vec{\eta}) = \left(\mathcal{Y} \right) \left(\frac{\partial G}{\partial \vec{\eta}} \right) dt$$

$$\frac{\partial \vec{\zeta}}{\partial \vec{\eta}} = \mathbb{1} + dt \underbrace{\left(\mathcal{Y} \right) \left(\frac{\partial^2 G}{\partial \eta_i \partial \eta_j} \right)}_{(M)}; \quad (M)^T = \mathbb{1} - dt \underbrace{\left(\frac{\partial^2 G}{\partial \eta_j \partial \eta_i} \right)}_{\text{same}} \left(\mathcal{Y} \right)$$

$$(M)^T (J) (M) = (J) + (J) dt (J) \left(\frac{\partial^2 G}{\partial \eta_i \partial \eta_j} \right) - \\ - dt \left(\frac{\partial^2 G}{\partial \eta_i \partial \eta_j} \right) (J) (J) \mathbb{1} = (J)$$

\Rightarrow volume in phase space also
doesn't change